# CS3383 Unit 4: dynamic multithreaded algorithms lecture 1 

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## Outline

Dynamic Multithreaded Algorithms
Race Conditions Scheduling

## Race Conditions

## Non-Determinism

- result varies from run to run
sometimes OK (in certain randomized algorithms)
- mostly a bug.


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## Non-Determinism

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sometimes OK (in certain randomized algorithms)
$>$ mostly a bug.

$$
\begin{aligned}
& x=0 \\
& \text { parallel for } i \leftarrow 1 \text { to } 2 \text { do } \\
& \quad x \leftarrow x+1
\end{aligned}
$$

$\checkmark$ nondeterministic unless incrementing $x$ is
atomic

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- all possible topological sorts are
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$>$ In particular it's not hard for both loads to complete before either store
- In practice there are various synchronization strategies (locks, etc...).
- Here we will insist that parallel strands are independent


## Racy demo

```
#pragma omp parallel for
    for (int i=0; i<10000; i ++){
        x ++ ;
    }
```

$>$ what is the final value of $x$ ?

## We can write bad code with spawn too

```
sum(i, j)
    if (i>j)
    return;
    if (i==j)
        x++;
    else
        m=(i+j)/2;
        spawn sum(i,m);
        sum(m+1,j);
        sync;
```

> here we have the same non-deterministic interleaving of reading and writing $x$
the style is a bit unnatural, in particular we are not using the return value of spawn at all.

## spawn race demo

static void
sum(long i, long j, long *out) \{
if (i>j)
return;
if (i==j) \{
(*out) ++ ;
\} else \{
long $m=(i+j) / 2$;
\#pragma omp task
sum (i,m,out);
sum (m+1, j, out);
\#pragma omp taskwait

## Being more functional helps

```
sum(i, j)
    if (i>j) return 0;
    if (i==j) return i;
    m}\leftarrow(i+j)/2
    left \leftarrow spawn sum(i,m);
    right \leftarrow sum(m+1,j);
    sync;
    return left + right;
```

- each strand writes into different variables


## Being more functional helps

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sum(i, j)
    if (i>j) return 0;
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    sync;
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```

- each strand writes into different variables
- sync is used as a barrier to serialize


## functional sum demo

```
long sum(long i, long j) {
    if (i>j) return 0;
    if (i==j) {
        return i;
    } else {
    long left,right,m=(i+j)/2;
#pragma omp task shared(left)
    left = sum(i,m);
    right = sum(m+1,j);
#pragma omp taskwait
    return left+right;
}
```


## Single Writer races

$>$ arguments to spawned routines are evaluated in the parent context

```
x & spawn foo(x)
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## Single Writer races

$>$ arguments to spawned routines are evaluated in the parent context
$>$ but this isn't enough to be race free.
$>$ which value $x$ is passed to the second call of 'foo' depends how long the first one takes.

$$
\begin{aligned}
& x \leftarrow \operatorname{spawn} \text { foo }(x) \\
& y \leftarrow \text { foo }(x) \\
& \text { sync }
\end{aligned}
$$

## Scheduling

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On-Line No advance knowledge of when threads will spawn or complete.
Distributed No central controller.

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## Ideal Scheduler

On-Line No advance knowledge of when threads will spawn or complete.
Distributed No central controller.
to simplify analysis, we relax the second condition

## A greedy centralized scheduler

Maintain a ready queue of strands ready to run.

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- To simplify analysis, split any non-unit strands into a chain of unit strands
- Therefore, after one time step, we schedule again.


## Optimal and Approximate Scheduling

Recall
(work law)
(span)
Therefore

$$
\begin{aligned}
& T_{p} \geq T_{1} / p \\
& T_{p} \geq T_{\infty}
\end{aligned}
$$

$$
T_{p} \geq \max \left(T_{1} / p, T_{\infty}\right)=\mathrm{opt}
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## Optimal and Approximate Scheduling Recall

(work law)
(span)
Therefore

$$
T_{p} \geq \max \left(T_{1} / p, T_{\infty}\right)=\mathrm{opt}
$$

With the greedy algorithm we can achieve

$$
T_{p} \leq \frac{T_{1}}{p}+T_{\infty} \leq 2 \max \left(T_{1} / p, T_{\infty}\right)=2 \times \mathrm{opt}
$$

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Let $k$ be the number of complete steps.

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$>$ Therefore $k \leq T_{1} / p$


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## Counting Incomplete Steps



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$>$ ready queue $=$ the set of sources in $G$
- In incomplete step runs all sources in $G$
$\rightarrow$ Every longest path starts at a source
- After an incomplete step, length of longest path shrinks by 1
$>$ There can be at most $T_{\infty}$ steps.


## Parallel Slackness

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\text { parallel slackness }=\frac{\text { parallelism }}{p}=\frac{T_{1}}{p T_{\infty}}
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- If slackness $<1$, speedup $<p$


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& \text { speedup }=\frac{T_{1}}{T_{p}} \leq \frac{T_{1}}{T_{\infty}}=p \times \text { slackness }
\end{aligned}
$$

$>$ If slackness $<1$, speedup $<p$

- If slackness $\geq 1$, linear speedup achievable for given number of processors


## Slackness and Scheduling

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## Theorem

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\begin{equation*}
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\end{equation*}
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With the greedy scheduler,

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$$

$$
T_{p} \leq\left(\frac{T_{1}}{p}+T_{\infty}\right)
$$

Substituting (1),

$$
T_{p} \leq \frac{T_{1}}{p}\left(1+\frac{1}{c}\right)
$$

