# CS3383 Unit 4: dynamic multithreaded algorithms lecture 1

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March 20, 2024



#### Outline

#### Dynamic Multithreaded Algorithms Race Conditions Scheduling

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# **Race Conditions**

#### Non-Determinism

result varies from run to run

sometimes OK (in certain randomized algorithms)

mostly a bug.

## **Race Conditions**

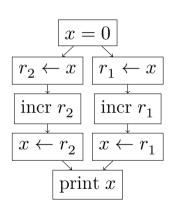
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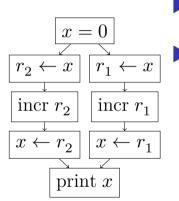
$$x = 0$$
  
parallel for i  $\leftarrow 1$  to 2 do  
 $x \leftarrow x + 1$ 

 nondeterministic unless incrementing x is atomic



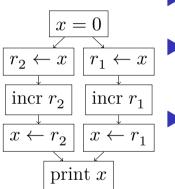
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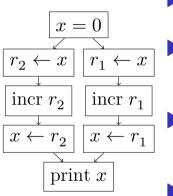


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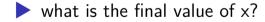


- all possible topological sorts are valid execution orders
  - In particular it's not hard for both loads to complete before either store
  - In practice there are various synchronization strategies (locks, etc...).
  - Here we will insist that parallel strands are independent



```
#pragma omp parallel for
  for (int i=0; i<10000; i++){
     x++;
  }</pre>
```

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#### We can write bad code with spawn too

sum(i, j) if (i>j)return: if (i==j) x++; else m = (i+j)/2;spawn sum(i,m); sum(m+1,j); sync;

 here we have the same non-deterministic interleaving of reading and writing x
 the style is a bit unnatural, in particular we are not using the return value of spawn at all.

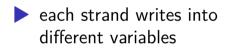
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#### spawn race demo

```
static void
sum(long i, long j, long *out) {
  if (i>j)
    return:
  if (i==j) {
    (*out) ++ ;
  } else {
    long m = (i+j)/2;
#pragma omp task
    sum(i,m,out);
    sum(m+1, j, out);
#pragma omp taskwait
```

### Being more *functional* helps

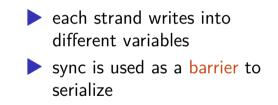
```
sum(i, j)
  if (i>j) return 0;
  if (i==j) return i;
  m \leftarrow (i+j)/2;
  left ← spawn sum(i,m);
  right \leftarrow sum(m+1,j);
  sync;
  return left + right;
```



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### Being more *functional* helps

left ← spawn sum(i,m); right ← sum(m+1,j); sync; return left + right;



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### functional sum demo

```
long sum(long i, long j) {
  if (i>j) return 0;
  if (i==j) {
    return i:
  } else {
    long left,right,m=(i+j)/2;
#pragma omp task shared(left)
    left = sum(i,m);
    right = sum(m+1, j);
#pragma omp taskwait
    return left+right;
```

### Single Writer races

arguments to spawned routines are evaluated in the parent context

x ← spawn foo(x) y ← foo(x) sync

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but this isn't enough to be race free.

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y ← foo(x)
sync
```

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# Single Writer races

x ← spawn foo(x) y ← foo(x) sync arguments to spawned routines are evaluated in the parent context

but this isn't enough to be race free.

which value x is passed to the second call of 'foo' depends how long the first one takes.

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# Scheduling

#### Scheduling Problem

Abstractly Mapping threads to processors Pragmatically Mapping logical threads to a thread pool.

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On-Line No advance knowledge of when threads will spawn or complete.

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#### Ideal Scheduler

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Distributed No central controller.

to simplify analysis, we relax the second condition

Maintain a *ready queue* of strands ready to run.

Scheduling Step

Complete Step If  $\geq p$  (# processors) strands are ready, assign p strands to processors.

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Scheduling Step

Complete Step If  $\geq p$  (# processors) strands are ready, assign pstrands to processors. Incomplete Step Otherwise, assign all waiting strands to processors

- To simplify analysis, split any non-unit strands into a chain of unit strands
- Therefore, after one time step, we schedule again.

Optimal and Approximate Scheduling Recall

(work law) (span)

$$T_p \ge T_1/p$$
$$T_p \ge T_\infty$$

Therefore

 $T_p \geq \max(T_1/p,T_\infty) = \mathsf{opt}$ 

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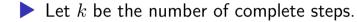
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Therefore

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With the greedy algorithm we can achieve

$$T_p \leq \frac{T_1}{p} + T_\infty \leq 2\max(T_1/p,T_\infty) = 2\times \operatorname{opt}$$



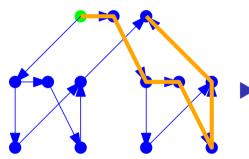
- $\blacktriangleright$  Let k be the number of complete steps.
- At each complete step we do p units of work.

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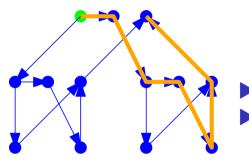
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 $\blacktriangleright \quad \text{Therefore } k \leq T_1/p$ 

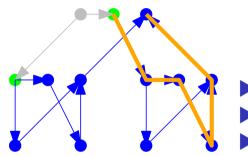


Let G be the DAG of *remaining strands*.

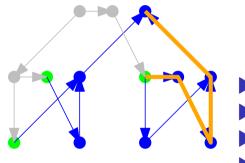


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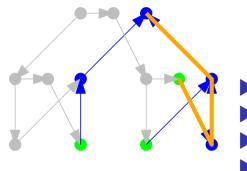
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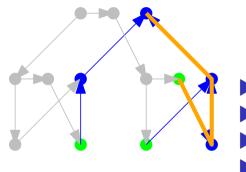


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Let G be the DAG of remaining strands.
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After an incomplete step, length of longest path shrinks by 1
 There can be at most T<sub>∞</sub> steps.

#### Parallel Slackness

parallel slackness = 
$$\frac{\text{parallelism}}{p} = \frac{T_1}{pT_{\infty}}$$



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$$\mathsf{speedup} = \frac{T_1}{T_p} \leq \frac{T_1}{T_\infty} = p \times \mathsf{slackness}$$

▶ If slackness < 1, speedup < p</li>
 ▶ If slackness ≥ 1, linear speedup achievable for given number of processors

$$\mathsf{slackness} := \frac{T_1}{p \times T_\infty}$$

#### Theorem

For suf. large slackness, greedy scheduler approaches time  $T_1/p$ .

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#### Suppose

$$T_1/(p\times T_\infty)\geq c$$

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Suppose

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$$T_p \leq \left(\frac{T_1}{p} + T_\infty\right)$$

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Substituting (1),

Suppose

$$T_1/(p\times T_\infty)\geq c$$

$$T_p \leq \frac{T_1}{p} \left(1 + \frac{1}{c}\right)$$

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