

CS3383 Unit 3: Dynamic Programming

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Outline

Dynamic Programming
Shortest path in DAG

March Break Hotels

Scenario

Wanted Cheap holiday

Costs Hotel + Taxi, no charge for inconvenience

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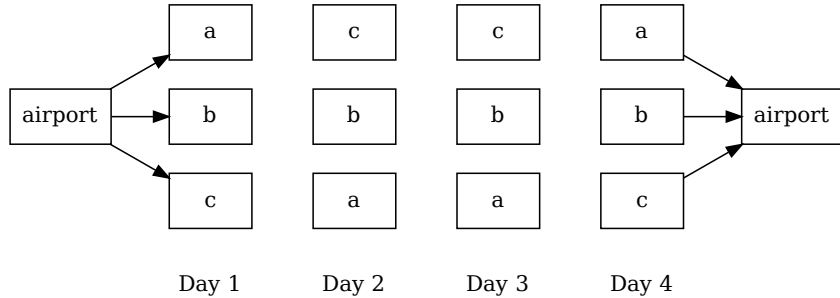
Taxi Cost					Hotel Price				
	a	b	c	aprt		1	2	3	4
a	0	10	30	50	a	100	100	100	100
b	10	0	30	50	b	80	40	120	120
c	30	30	0	50	c	50	80	80	80
aprt	50	50	50	0					

It's a trap!

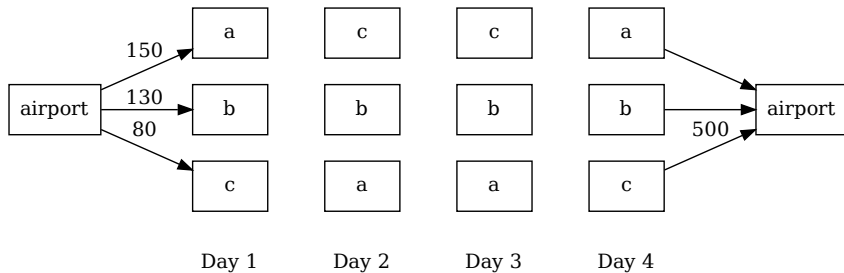
	Hotel Price			
	1	2	3	4
a	100	100	100	100
b	80	40	120	120
c	50	80	80	80

	Taxi Cost			
	a	b	c	airport
a	0	10	30	50
b	10	0	30	50
c	1000	1000	0	500
airport	50	50	50	0

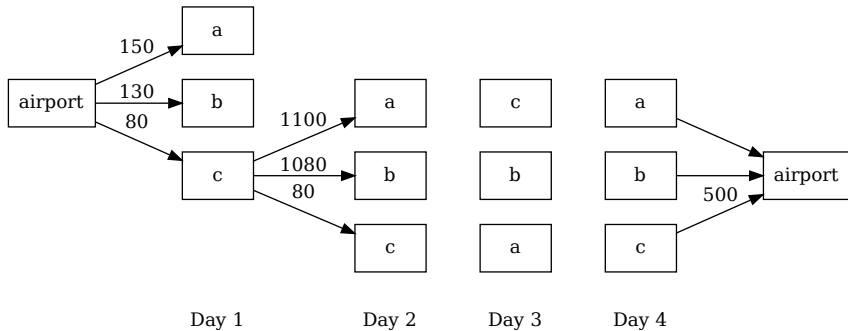
Let's get graphical



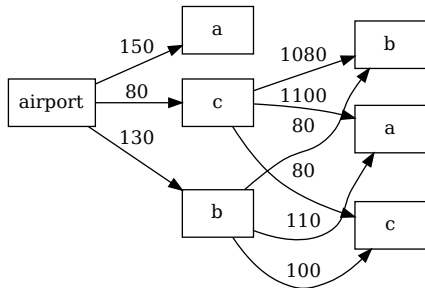
Let's get graphical



Let's get graphical



Let's get graphical



Day 1

Day 2

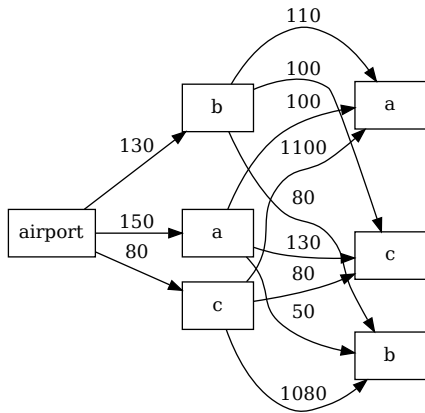


Day 3



Day 4

Let's get graphical



Day 1

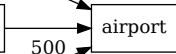
Day 2



Day 3



Day 4



Dijkstra considered overkill

- ▶ There are no negative edge weights, so shortest path is tractable.
- ▶ Even better, we have an *acyclic* graph (why?)
- ▶ So we find a shortest path in linear time after *topological sorting*.

“Recursive” topological sort

Recursive “algorithm”

1. Remove a *source* from the DAG, and put it first.
2. Topologically sort the remaining graph.

► how to quickly find a source?

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1. Remove a *source* from the DAG, and put it first.
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- ▶ how to quickly find a source?
- ▶ Use some auxiliary data structure to track sources across iterations

Using a Queue

BFS-like topological sort

```
1: function TOPSORT(G)
2:    $Q \leftarrow$  All Sources
3:   while !empty(Q) do
4:      $v \leftarrow \text{deq}(Q)$ 
5:
6:
7:   end while
8: end function
```

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5:     Output  $v$   
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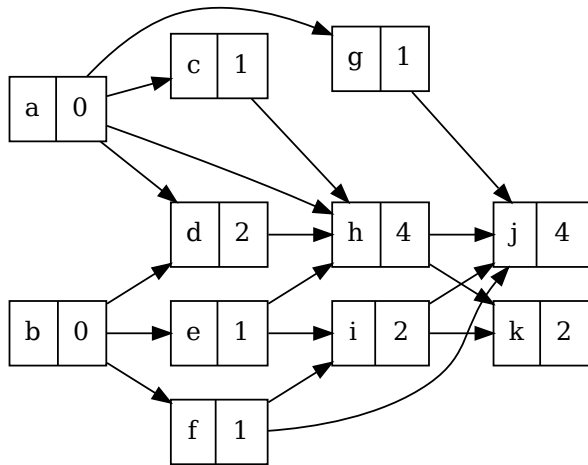
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BFS-like topological sort

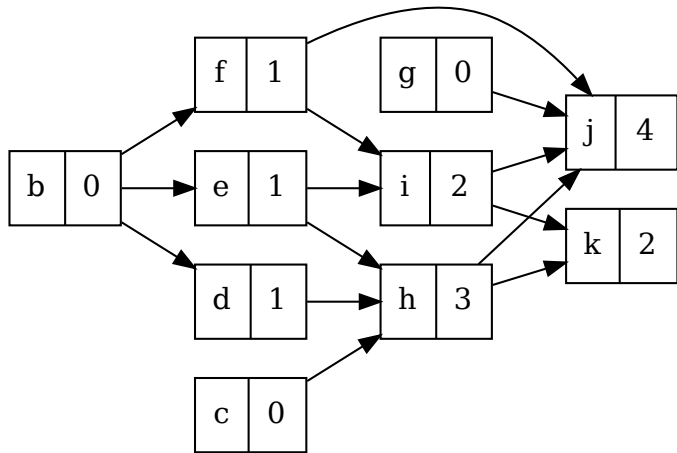
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► What is the complexity of step 6?

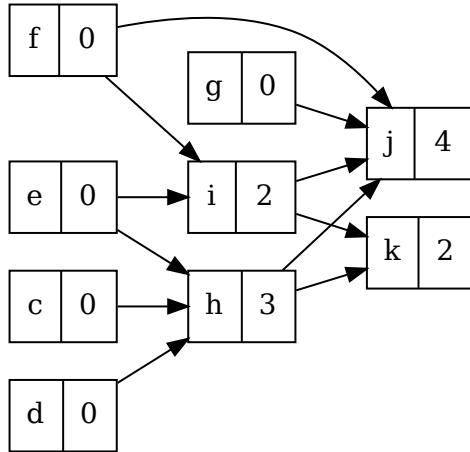
Topological sort with counters



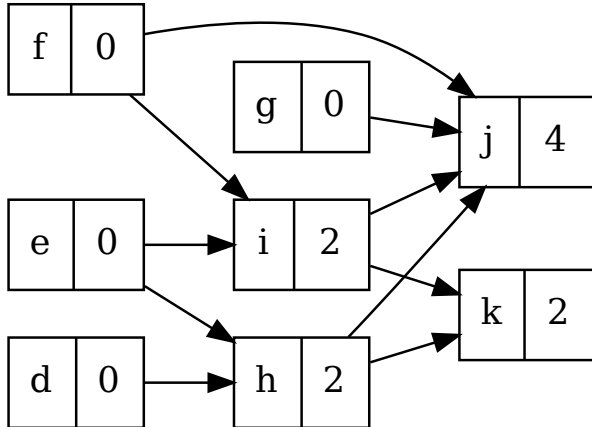
Topological sort with counters



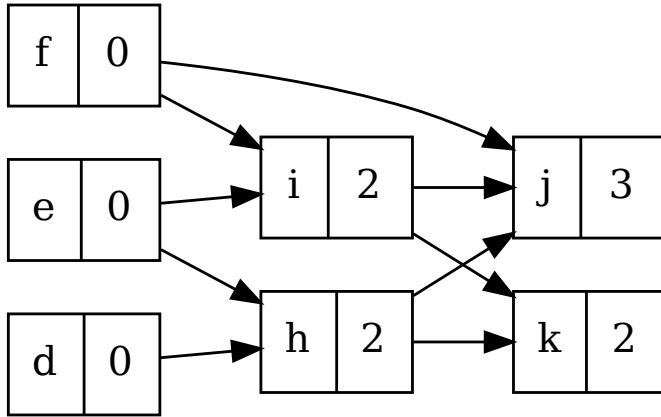
Topological sort with counters



Topological sort with counters



Topological sort with counters



No priority queue needed

```
while len(Q) > 0:
    v = Q.popleft()
    rank[v] = len(output)
    output.append(v)
    for (u, _) in G[v]:
        count[u] -= 1
        if count[u] == 0:
            Q.append(u)
```

Shortest Paths in DAGs

- ▶ Every path in a DAG goes through nodes in linearized (topological sort) order.

```
for j in range(rank[root]+1,n):  
    v = order[j]  
    for (prev,w) in In[v]:  
        if w+dist[prev] < dist[v]:  
            dist[v]=w+dist[prev]
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Shortest Paths in DAGs

- ▶ Every path in a DAG goes through nodes in linearized (topological sort) order.
- ▶ *every node is reached via its predecessors*
- ▶ So we need a single loop after sorting.

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What makes this *Dynamic Programming*?

Ordered Subproblems

In order to solve our problem in a single pass, we need

- ▶ An ordered set of subproblems $L(i)$

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Ordered Subproblems

In order to solve our problem in a single pass, we need

- ▶ An ordered set of subproblems $L(i)$
- ▶ Each subproblem $L(i)$ can be solved using only the answers for $L(j)$, for $j < i$.